Rebecca Foust Lightning Talk

- PhD Candidate and NASA Space Technology Research Fellow at UIUC
- Special Student at Caltech
- Research Focus: Multi-Agent Optimal Guidance and Control
- Past Autonomy Projects:
  - Swarm Orbital Construction Algorithm
  - Fast Motion Planning
  - Fast Lightweight Autonomy Drone

https://youtu.be/62cngDR1k-E

Optimal Motion Planning (1.5x)